

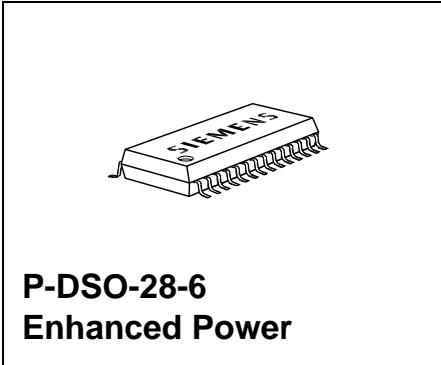
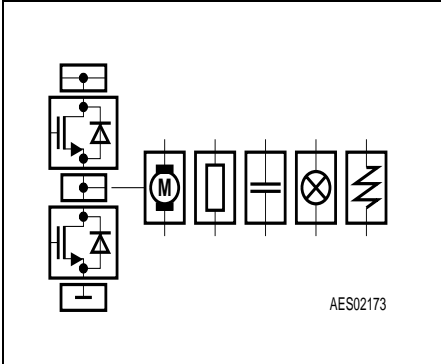
1-A Hex-Half-Bridge / Double Six-Driver

TLE 5208-6 G

Overview

Features

- Six High-Side and six Low-Side-Drivers
- Free configurable as switch, half-bridge or H-bridge
- Optimized for DC motor management applications
- 0.6 A continuous (1 A peak) current per switch
- $R_{DS\ ON}$; typ. 1 Ω , @ 25 °C per switch
- Output: short-circuit protected and diagnosis
- Over-Temperature-Protection with hysteresis and diagnosis
- Standard SPI-Interface
- Very low current consumption (typ. 20 μ A, @ 25 °C) in stand-by (Inhibit) mode
- Over- and Under-Voltage-Lockout
- CMOS/TTL compatible inputs with hysteresis
- No crossover current
- Internal clamp diodes
- Enhanced power P-DSO-Package



Type	Ordering Code	Package
TLE 5208-6 G	Q67007-A9282	P-DSO-28-6

Description

The TLE 5208-6 G is a fully protected **Hex-Half-Bridge-Driver** designed specifically for automotive and industrial motion control applications. The part is based on the Siemens power technology SPT® which allows bipolar and CMOS control circuitry in accordance with DMOS power devices existing on the same monolithic circuitry.

The six low and high side drivers are free configurable and can be controlled separately. Therefore all kind of loads can be combined. In motion control up to 5 actuators (DC-Motors) can be connected to the 6 half-bridge-outputs (cascade configuration). Operation modes forward (cw), reverse (ccw), brake and high impedance are controlled from a standard SPI-Interface. The possibility to control the outputs via software from a central logic, allows limiting the power dissipation. So the standard P-DSO-28-6-package meets the application requirements and saves PCB-Board-space and cost.

Furthermore the build-in features like Over- and Under-Voltage-Lockout, Over-Temperature-Protection and the very low quiescent current in stand-by mode opens a wide range of automotive- and industrial-applications.

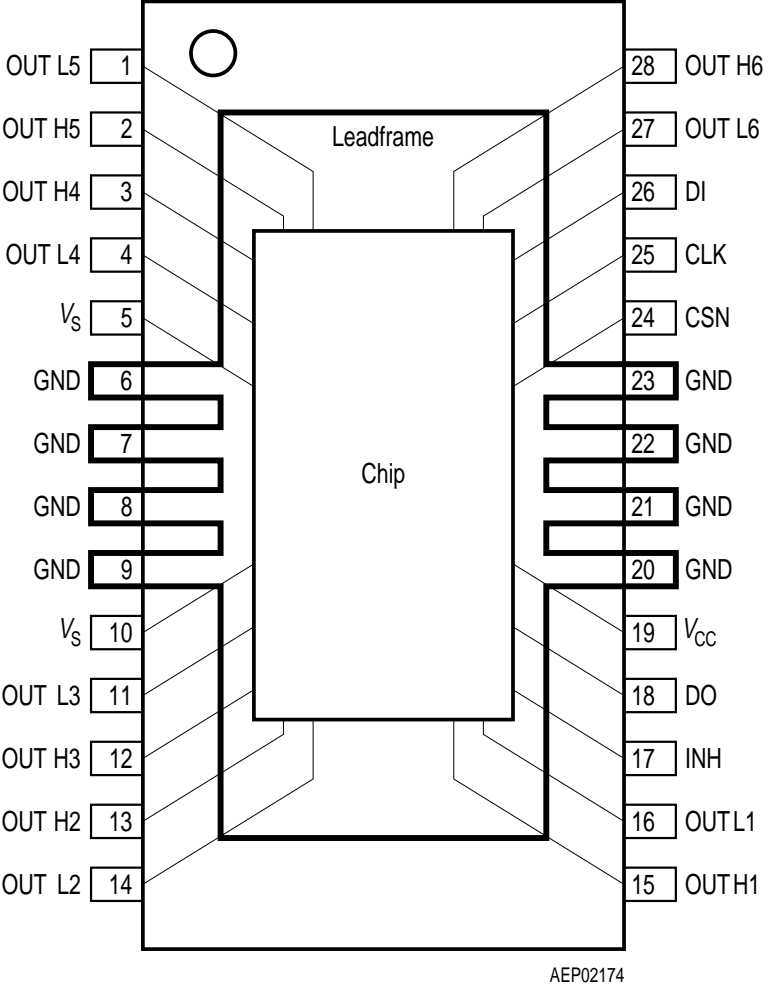


Figure 1 Pin Configuration (top view)

Pin Definitions and Functions

Pin No.	Symbol	Function
1	OUTL5	Low-Side-Output 5 ; Power-MOS open drain with internal reverse diode; no internal clamp diode or active zenering; short-circuit protected and open load controlled.
2	OUTH5	High-Side-Output 5 ; Power-MOS open source with internal reverse diode; no internal clamp diode or active zenering; short-circuit protected and open load controlled.
3	OUTH4	High-Side-Output 4 ; see pin2.
4	OUTL4	Low-Side-Output 4 ; see pin1.
5	V_s	Power supply ; external connection to pin 10 necessary; needs a blocking capacitor as close as possible to GND; Value: 22 μ F electrolytic in parallel to 220 nF ceramic.
6, 7, 8, 9	GND	Ground ; reference potential; internal connection to pin 20, 21, 22 and 23; cooling tab; to reduce thermal resistance; place cooling areas on PCB close to this pins.
10	V_s	Power Supply ; see pin 5.
11	OUTL3	Low-Side-Output 3 ; see pin1.
12	OUTH3	High-Side-Output 3 ; see pin2.
13	OUTH2	High-Side-Output 2 ; see pin2.
14	OUTL2	Low-Side-Output 2 ; see pin1.
15	OUTH1	High-Side-Output 1 ; see pin2.
16	OUTL1	Low-Side-Output 1 ; see pin1.
17	INH	Inhibit input ; has an internal pull down; device is switched in standby condition by pulling the INH terminal low.
18	DO	Serial-Data-Output ; this 3-state output transfers diagnosis data to the control device; the output will remain 3-stated unless the device is selected by a low on Chip-Select-Not (CSN); see table at page 8 for Diagnosis protocol.
19	V_{cc}	Logic supply voltage ; needs a blocking capacitor as close as possible to GND; Value: 10 μ F electrolytic in parallel to 220 nF ceramic.

Pin Definitions and Functions (cont'd)

Pin No.	Symbol	Function
20, 21, 22, 23	GND	Ground
24	CSN	Chip-Select-Not input ; CSN is an active low input; serial communication is enabled by pulling the CSN terminal low; CSN input should only be transitioned when CLK is low; CSN has an internal active pull up and requires CMOS logic level inputs.
25	CLK	Serial clock input ; clocks the shiftregister; CLK has an internal active pull down and requires CMOS logic level inputs.
26	DI	Serial data input ; receives serial data from the control device; serial data transmitted to DI is an 16-bit control word with the Least Significant Bit (LSB) being transferred first: the input has an active pull down and requires CMOS logic level inputs; DI will accept data on the falling edge of CLK-signal; see table at page 8 for input data protocol.
27	OUTL6	Low-Side-Output 6 ; see pin1.
28	OUTH6	High-Side-Output 6 ; see pin2.

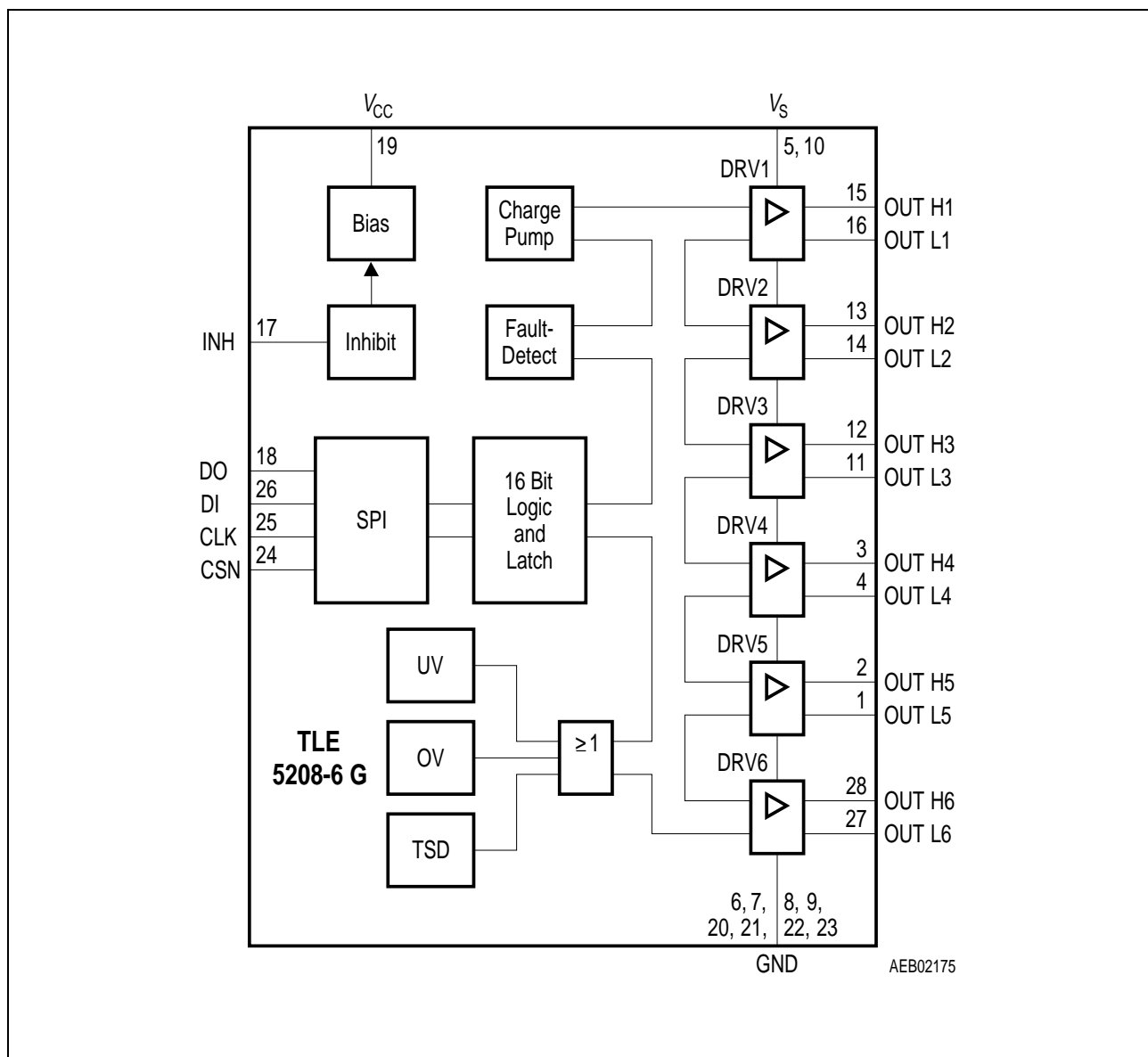


Figure 2 Block Diagram

Circuit Description

Figure 2 shows a block schematic diagram of the module.

There are 6 half-bridge-drivers on the right-hand side. An HS driver and an LS driver are combined to form a half-bridge-driver in each case.

The drivers communicate via the internal data bus with the logic and the other control and monitoring functions: under-voltage (UV), over-voltage (OV), over-temperature (TSD), charge pump and fault detect.

Two connection interfaces are provided for supply to the module: All power drivers are connected to the supply voltage V_S . These are monitored by over-voltage and under-

voltage comparators with hysteresis, so that the correct function can be checked in the application at any time.

The logic is supplied by the V_{CC} voltage, typ. with 5 V. The V_{CC} voltage uses an internally generated Power-On Reset (POR) to initialize the module at power-on. The advantage of this system is that information stored in the logic remains intact in the event of short-term failures in the supply voltage V_S . The system can therefore continue to operate following V_S under-voltage, without having to be reprogrammed. The “under-voltage” information is stored, and can be read out via the interface. The same logically applies for over-voltage. “Interference spikes” on V_S are therefore effectively suppressed.

The situation is different in the case of under-voltage on the V_{CC} connection pin. If this occurs, then the internally stored data is deleted, and the output levels are switched to high-impedance status (tristate). The module is initialized by V_{CC} following restart (Power-On Reset = POR).

The 16-bit wide programming word or control word (see table at **page 8**) is read in via the DI data input, and this is synchronized with the clock input CLK. The status word appears synchronously at the DO data output (see table at **page 8**).

The transmission cycle begins when the chip is selected with the CSN input (H to L). If the CSN input changes from L to H then the word which has been read-in becomes the control word. The DO output switches to tristate status at this point, thereby releasing the DO bus circuit for other uses.

The INH inhibit input can be used to cut off the complete module. This reduces the current consumption to just a few μA , and results in the loss of any data stored. The output levels are switched to tristate status. The module is reinitialized with the internally generated POR (Power-On Reset) at restart.

This feature allows the use of this module in battery-operated applications (vehicle body control applications).

Every driver block from DRV 1 to 6 contains a low-side driver and a high-side driver. The output connections have been selected so that each HS driver and LS driver pair can be combined to form a half-bridge by short-circuiting adjacent connections. The full flexibility of the configuration can be achieved by dissecting the half-bridges into “quarter-bridges”.

Figure 3 shows examples of possible applications.

When commutating inductive loads, the dissipated power peak can be significantly reduced by activating the transistor located parallel to the internal freewheeling diode. A special, integrated “timer” for power ON/OFF times ensures there is no crossover current at the half-bridge.

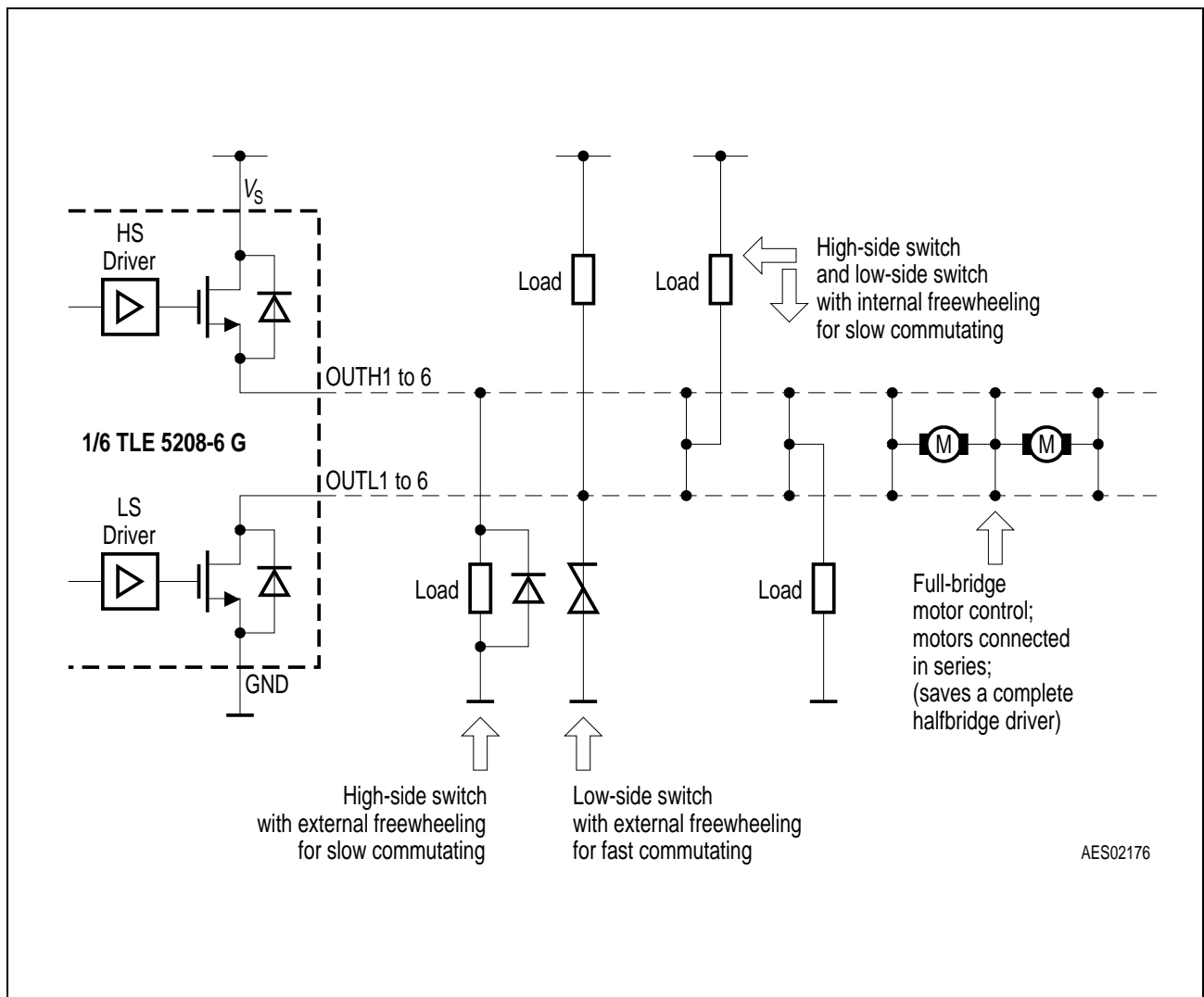


Figure 3 Configuration Examples for “Quarter Bridges” on the TLE 5208-6 G

Input Data Protocol

BIT	
15	OVLO on/off
14	not used
13	Overcurrent SD on/off
12	HS-Switch 6
11	LS-Switch 6
10	HS-Switch 5
9	LS-Switch 5
8	HS-Switch 4
7	LS-Switch 4
6	HS-Switch 3
5	LS-Switch 3
4	HS-Switch 2
3	LS-Switch 2
2	HS-Switch 1
1	LS-Switch 1
0	Status Register Reset

H = ON
L = OFF

Diagnosis Data Protocol

BIT	
15	Power supply fail
14	Underload
13	Overload
12	Status HS-Switch 6
11	Status LS-Switch 6
10	Status HS-Switch 5
9	Status LS-Switch 5
8	Status HS-Switch 4
7	Status LS-Switch 4
6	Status HS-Switch 3
5	Status LS-Switch 3
4	Status HS-Switch 2
3	Status LS-Switch 2
2	Status HS-Switch 1
1	Status LS-Switch 1
0	Temp. Prewarning

H = ON
L = OFF

Fault Result Table

Fault	Diag.-Bit	Result
Overcurrent (load)	13	Only the failed output is switched OFF. Function can be deactivated by bit No. 13.
Short-circuit to GND (high-side-switch)	13	Only the failed output is switched OFF. Function can be deactivated by bit No. 13.
Short-circuit to V_S (low-side-switch)	13	Only the failed output is switched OFF. Function can be deactivated by bit No. 13.
Temperature warning	0	Reaction of control device needed.
Temperature shut down (SD)	–	All outputs OFF.
Openload	14	Reaction of control device needed.
Underload	14	Reaction of control device needed.
Under-voltage-lockout (UVLO)	15	All outputs OFF.
Over-voltage-lockout (OVLO)	15	All outputs OFF. Function can be deactivated by bit No. 15.

H = failure;
L = no failure.

Electrical Characteristics

Absolute Maximum Ratings

Parameter	Symbol	Limit Values		Unit	Remarks
		min.	max.		

Voltages

Supply voltage	V_S	- 0.3	40	V	—
Supply voltage	V_S	- 1	—	V	$t < 0.5 \text{ s}; I_S > - 2 \text{ A}$
Logic supply voltage	V_{CC}	- 0.3	7	V	$0 \text{ V} < V_S < 40 \text{ V}$
Logic input voltages (DI, CLK, CSN, INH)	V_I	- 0.3	7	V	$0 \text{ V} < V_S < 40 \text{ V}$ $0 \text{ V} < V_{CC} < 7 \text{ V}$
Logic output voltage (DO)	V_{DO}	- 0.3	V_{CC}	V	$0 \text{ V} < V_S < 40 \text{ V}$ $0 \text{ V} < V_{CC} < 7 \text{ V}$

Currents

Output current (cont.)	I_{OUT1-6}	—	—	A	internal limited; see overcurrent section
Output current (peak)	I_{OUT1-6}	—	—	A	internal limited; see overcurrent section

Temperatures

Junction temperature	T_j	- 40	150	°C	—
Storage temperature	T_{stg}	- 50	150	°C	—

Note: Maximum ratings are absolute ratings; exceeding any one of these values may cause irreversible damage to the integrated circuit.

Operating Range

Parameter	Symbol	Limit Values		Unit	Remarks
		min.	max.		
Supply voltage	V_S	$V_{UV\ OFF}$	40	V	After V_S rising above $V_{UV\ ON}$
Supply voltage slew rate	dV_S/dt	–	10	V/ μ s	–
Logic supply voltage	V_{CC}	4.75	5.5	V	–
Supply voltage increasing	V_S	– 0.3	$V_{UV\ ON}$	V	Outputs in tristate
Supply voltage decreasing	V_S	– 0.3	$V_{UV\ OFF}$	V	Outputs in tristate
Logic input voltage (DI,CLK,CSN,INH)	V_I	– 0.3	V_{CC}	V	–
SPI clock frequency	f_{CLK}	–	1	MHz	–
Junction temperature	T_j	– 40	150	°C	–

Thermal Resistances

Junction pin	$R_{thj-pin}$	–	25	K/W	measured to pin 7
Junction ambient	R_{thjA}	–	65	K/W	–

Electrical Characteristics

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; – 40 °C < T_j < 150 °C; unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		

Current Consumption

Quiescent current	I _S	–	20	50	μA	INH = Low; V _S = 13.2 V
Quiescent current	I _S	–	20	30	μA	INH = Low; V _S = 13.2 V; T _j = 25 °C
Logic-Supply current	I _{CC}	–	–	20	μA	INH = Low
Logic-Supply current	I _{CC}	–	2.5	6	mA	all HS-Switches ON
Supply current	I _S	–	2	5	mA	–

Over- and Under-Voltage Lockout

UV-Switch-ON voltage	V _{UV ON}	–	6.5	7	V	V _S increasing
UV-Switch-OFF voltage	V _{UV OFF}	5.5	6	–	V	V _S decreasing
UV-ON/OFF-Hysteresis	V _{UV HY}	–	0.5	–	V	V _{UV ON} – V _{UV OFF}
OV-Switch-OFF voltage	V _{OV OFF}	34	37	40	V	V _S increasing
OV-Switch-ON voltage	V _{OV ON}	28	32	36	V	V _S decreasing
OV-ON/OFF-Hysteresis	V _{OV HY}	–	5	–	V	V _{OV OFF} – V _{OV ON}

Electrical Characteristics (cont'd)

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; – 40 °C < T_j < 150 °C; unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		

Outputs OUTH1-6 and OUTL1-6**Static Drain-Source-On Resistance**

Source (High-Side) $I_{OUT} = -0.5$ A	$R_{DS\ ON\ H}$	–	1	1.5	Ω	8 V < V_S < 40 V $T_j = 25$ °C
			–	2.5	Ω	8 V < V_S < 40 V
			2	–	Ω	$V_{S\ OFF} < V_S \leq 8$ V $T_j = 25$ °C
			–	4	Ω	$V_{S\ OFF} < V_S \leq 8$ V
Sink (Low-Side) $I_{OUT} = 0.5$ A	$R_{DS\ ON\ L}$	–	1	1.5	Ω	8 V < V_S < 40 V $T_j = 25$ °C
			–	2.5	Ω	8 V < V_S < 40 V
			2	–	Ω	$V_{S\ OFF} < V_S \leq 8$ V $T_j = 25$ °C
			–	4	Ω	$V_{S\ OFF} < V_S \leq 8$ V

Leakage Current

Source-Output-Stage 1 to 6	I_{QLH}	– 1	–	–	mA	$V_{OUTH1-6} = 0$ V
Sink-Output-Stage 1 to 6	I_{QLL}	–	–	1	mA	$V_{OUTL1-6} = V_S$

Overcurrent

Source shutdown threshold	I_{SDU}	– 2	– 1.5	– 1	A	–
Sink shutdown threshold	I_{SDL}	1	1.5	2	A	–
Current limit	I_{OCL}	–	3	5	A	sink and source
Shutdown delay time	t_{dSD}	25	50	80	μ s	sink and source

Electrical Characteristics (cont'd)

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; – 40 °C < T_j < 150 °C; unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		

Open Circuit

Detection current	I _{OC} D	10	40	100	mA	–
Delay time	t _d OC	200	350	500	μs	–

Delay Time from Stand-by to Data In

Setup time	t _{set}	–	–	100	μs	–
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Output Delay Times; V_S = 13.2 V; R_{Load} = 25 Ω (device not in stand-by for t > 1 ms)

Source ON	t _d ON H	–	5	20	μs	–
Source OFF	t _d OFF H	–	4	20	μs	–
Sink ON	t _d ON L	–	6	30	μs	–
Sink OFF	t _d OFF L	–	2	10	μs	–
Dead time	t _D HL	1	–	–	μs	t _d ON L – t _d OFF H
Dead time	t _D LH	1	–	–	μs	t _d ON H – t _d OFF L

Output Switching Times; V_S = 13.2 V; R_{Load} = 25 Ω (device not in stand-by for t > 1 ms)

Source ON	t _{ON} H	–	6	30	μs	–
Source OFF	t _{OFF} H	–	1	5	μs	–
Sink ON	t _{ON} L	–	2.5	10	μs	–
Sink OFF	t _{OFF} L	–	1	5	μs	–

Clamp Diodes Forward Voltage

Upper	V _{FU}	–	1	1.5	V	I _F = 0.5 A
Lower	V _{FL}	–	1	1.5	V	I _F = 0.5 A

Electrical Characteristics (cont'd)

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; – 40 °C < T_j < 150 °C; unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		

Inhibit Input

H-input voltage threshold	V _{IH}	–	–	0.7	V _{CC}	–
L-input voltage threshold	V _{IL}	0.2	–	–	V _{CC}	–
Hysteresis of input voltage	V _{IHY}	50	200	500	mV	–
Pull down current	I _I	10	25	50	μA	V _I = 0.2 × V _{CC}
Input capacitance	C _I	–	10	15	pF	0 V < V _{CC} < 5.25 V

SPI-Interface

Logic Inputs DI, CLK and CSN

H-input voltage threshold	V _{IH}	–	–	0.7	V _{CC}	–
L-input voltage threshold	V _{IL}	0.2	–	–	V _{CC}	–
Hysteresis of input voltage	V _{IHY}	50	200	500	mV	–
Pull up current at pin CSN	I _{ICSN}	– 50	– 25	– 10	μA	V _{CSN} = 0.7 × V _{CC}
Pull down current at pin DI	I _{IDI}	10	25	50	μA	V _{DI} = 0.2 × V _{CC}
Pull down current at pin CLK	I _{ICLK}	10	25	50	μA	V _{CLK} = 0.2 × V _{CC}
Input capacitance at pin CSN, DI or CLK	C _I	–	10	15	pF	0 V < V _{CC} < 5.25 V

Logic Output DO

H-output voltage level	V _{DOH}	V _{CC} – 1.0	V _{CC} – 0.7	–	V	I _{DOH} = 1 mA
L-output voltage level	V _{DOL}	–	0.2	0.4	V	I _{DOL} = – 1.6 mA
Tristate leakage current	I _{DOLK}	– 10	–	10	μA	V _{CSN} = V _{CC} 0 V < V _{DO} < V _{CC}

Electrical Characteristics (cont'd)

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; $-40\text{ }^{\circ}\text{C} < T_j < 150\text{ }^{\circ}\text{C}$;
unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		
Tristate input capacitance	C_{DO}	–	10	15	pF	$V_{CSN} = V_{CC}$ $0\text{ V} < V_{CC}$ < 5.25 V

Data Input Timing

Clock period	t_{pCLK}	1000	–	–	ns	–
Clock high time	t_{CLKH}	500	–	–	ns	–
Clock low time	t_{CLKL}	500	–	–	ns	–
Clock low before CSN low	t_{bef}	500	–	–	ns	–
CSN setup time	t_{lead}	500	–	–	ns	–
CLK setup time	t_{lag}	500	–	–	ns	–
Clock low after CSN high	t_{beh}	500	–	–	ns	–
DI setup time	t_{DISU}	250	–	–	ns	–
DI hold time	t_{DIHO}	250	–	–	ns	–
Input signal rise time at pin DI, CLK and CSN	t_{rIN}	–	–	200	ns	–
Input signal fall time at pin DI, CLK and CSN	t_{fIN}	–	–	200	ns	–

Data Output Timing

DO rise time	t_{rDO}	–	50	100	ns	$C_L = 100\text{ pF}$
DO fall time	t_{fDO}	–	50	100	ns	$C_L = 100\text{ pF}$
DO enable time	t_{ENDO}	–	–	250	ns	low impedance
DO disable time	t_{DISDO}	–	–	250	ns	high impedance
DO valid time	t_{VADO}	–	100	250	ns	$V_{DO} < 0.1 V_{CC}$; $V_{DO} > 0.9 V_{CC}$; $C_L = 100\text{ pF}$

Electrical Characteristics (cont'd)

8 V < V_S < 40 V; 4.75 V < V_{CC} < 5.25 V; INH = High; all outputs open; – 40 °C < T_j < 150 °C; unless otherwise specified

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		

Thermal Prewarning and Shutdown

Thermal prewarning junction temperature	T_{jPW}	120	145	170	°C	–
Temperature prewarning hysteresis	ΔT	–	30	–	K	–
Thermal shutdown junction temperature	T_{jSD}	150	175	200	°C	–
Thermal switch-on junction temperature	T_{jSO}	120	–	170	°C	–
Temperature shutdown hysteresis	ΔT	–	30	–	K	–
Ratio of SD to PW temperature	T_{jSD} / T_{jPW}	1.05	1.20	–	–	–

Timing Diagrams

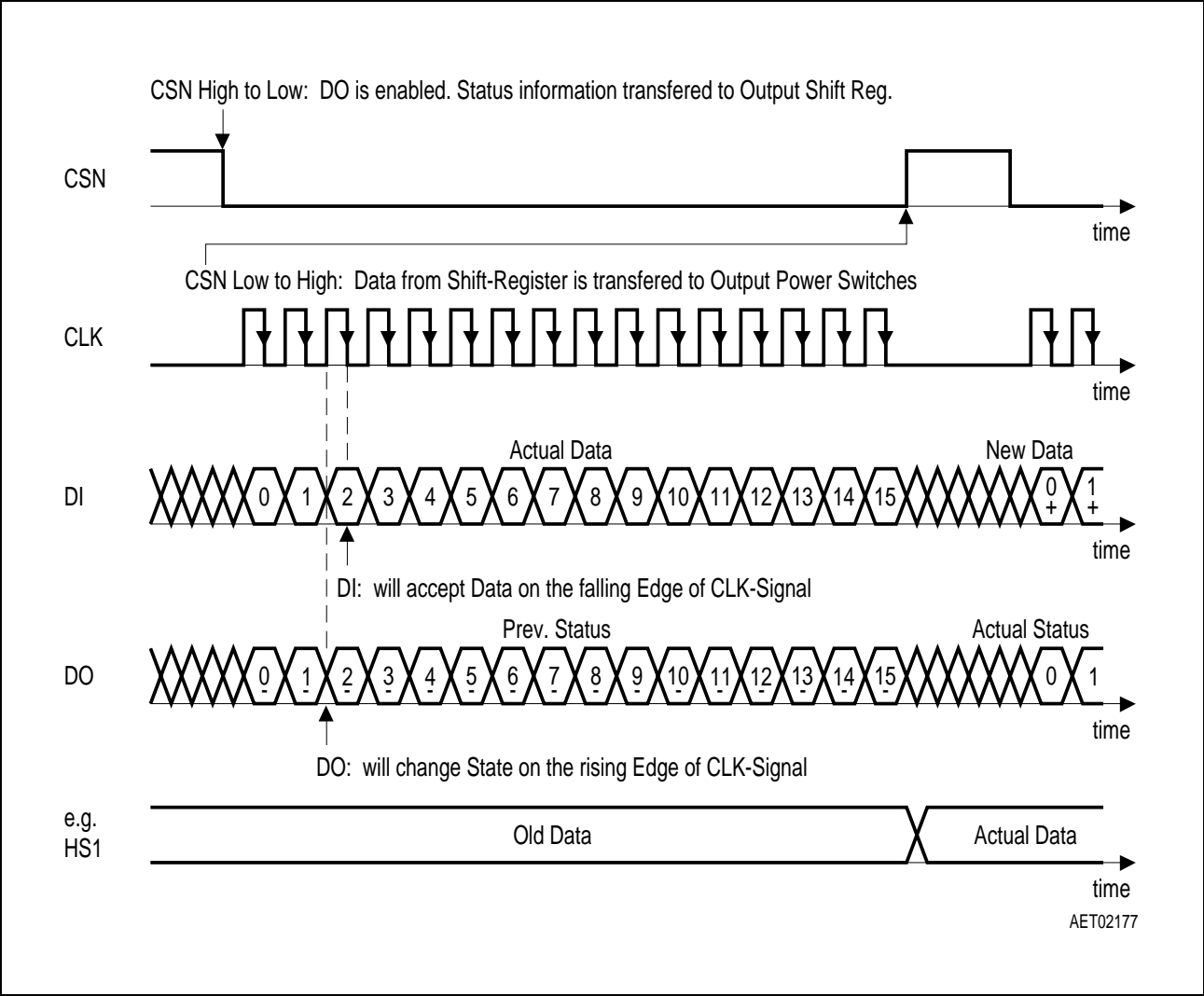


Figure 4 Data Transfer Timing

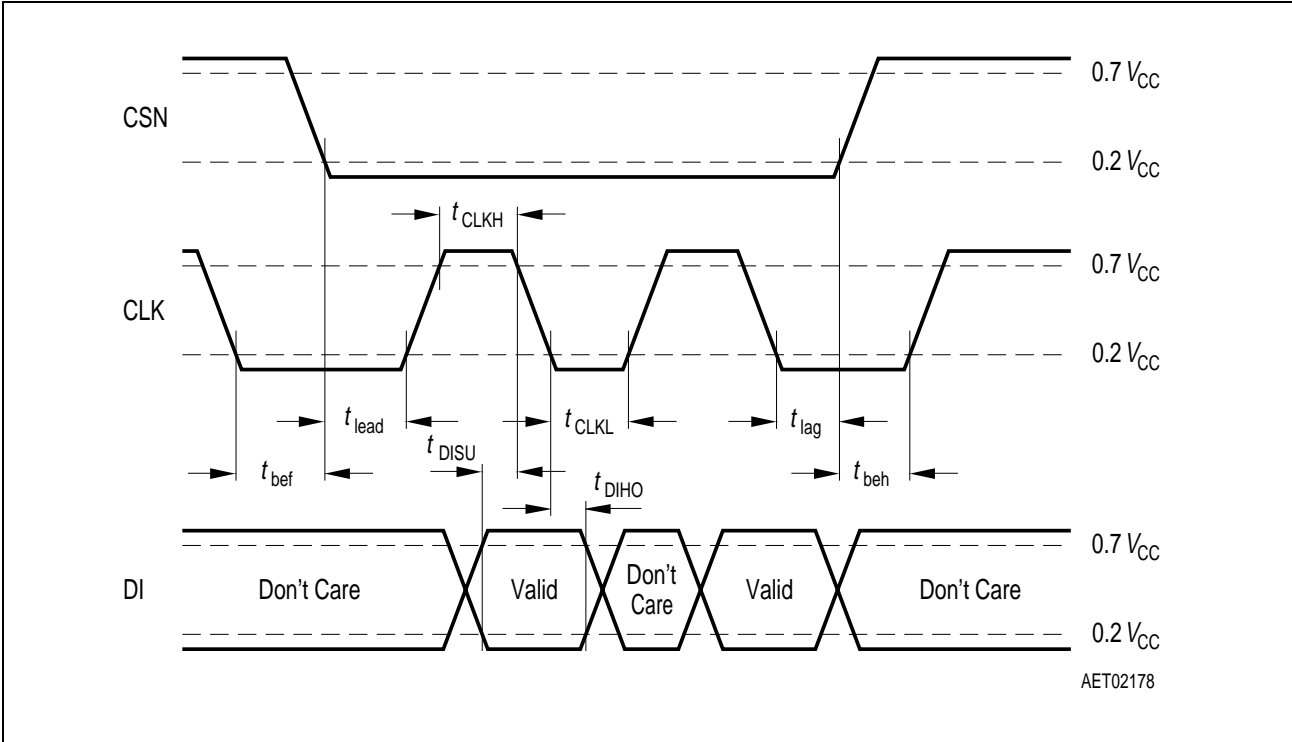


Figure 5 SPI-Input Timing

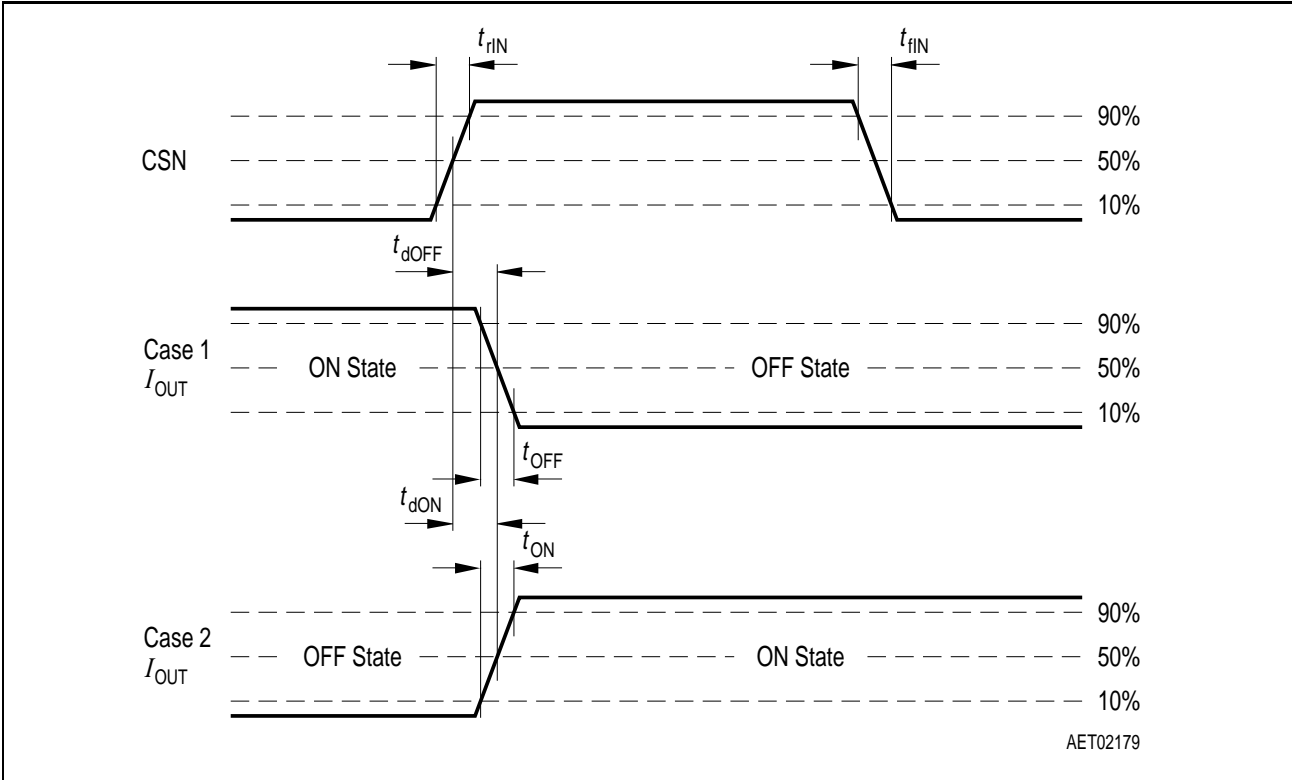


Figure 6 Turn OFF/ON Time

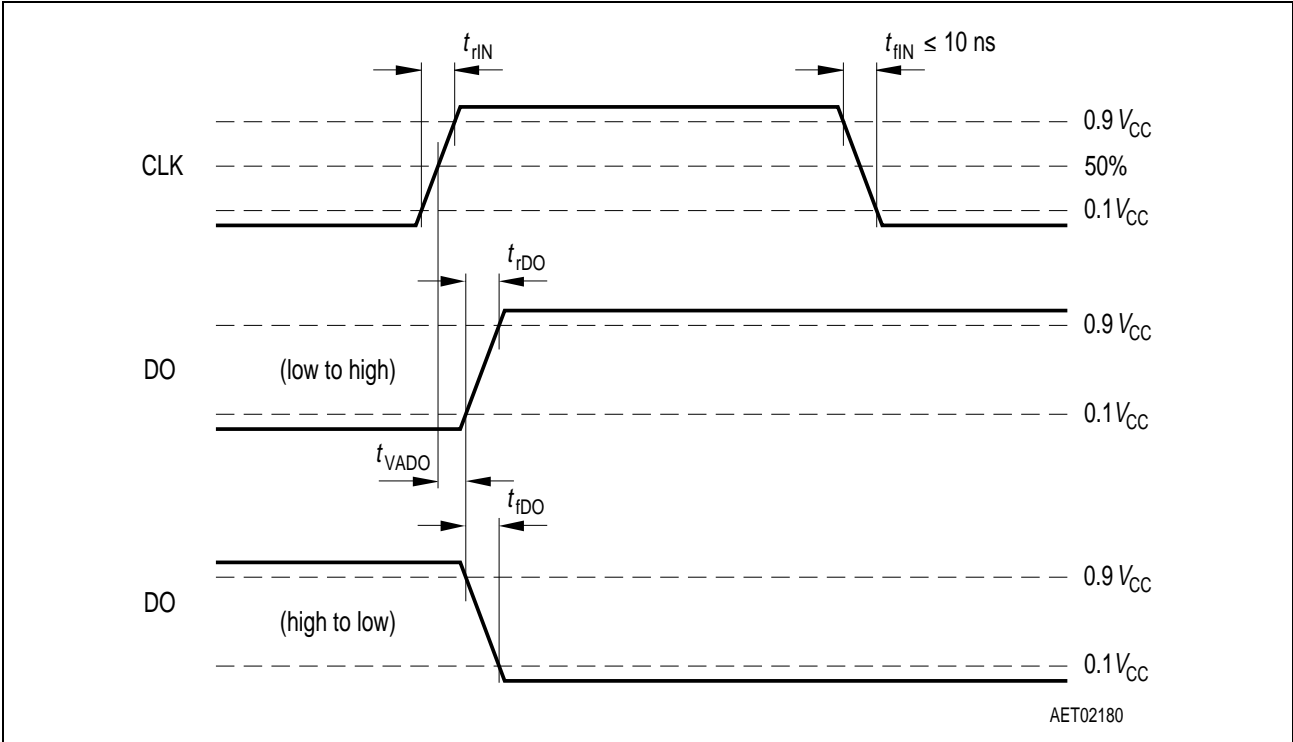


Figure 7 DO Valid Data Delay Time and Valid Time

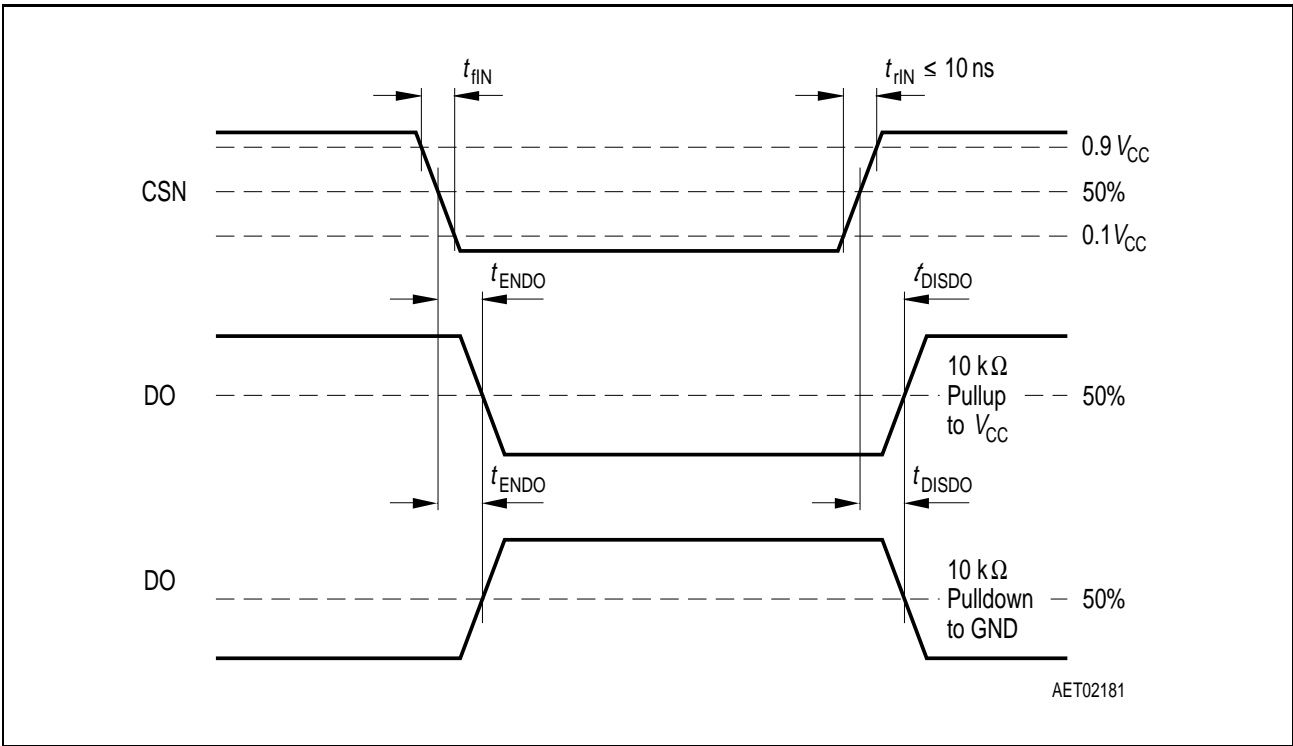


Figure 8 DO Enable and Disable Time

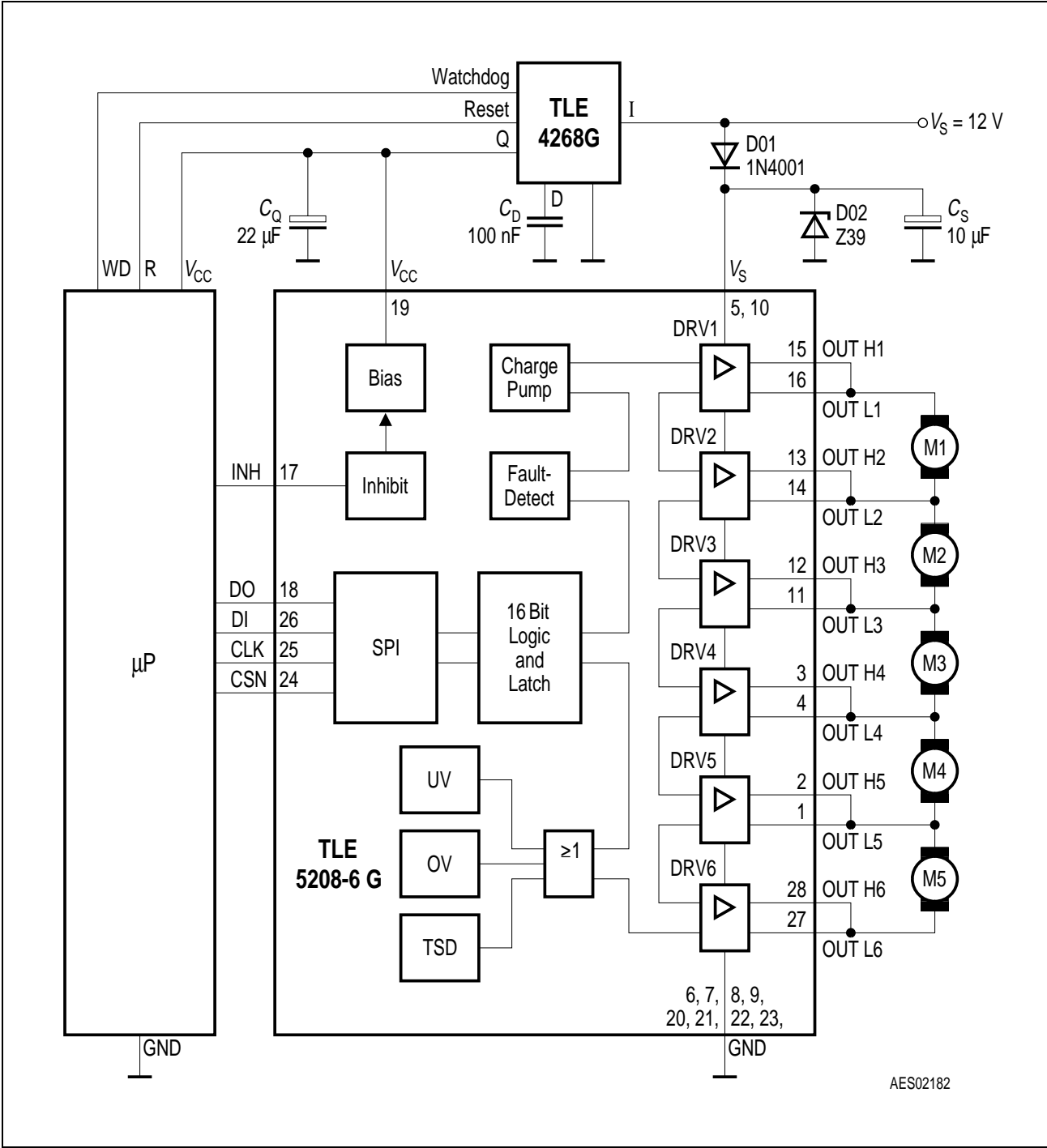
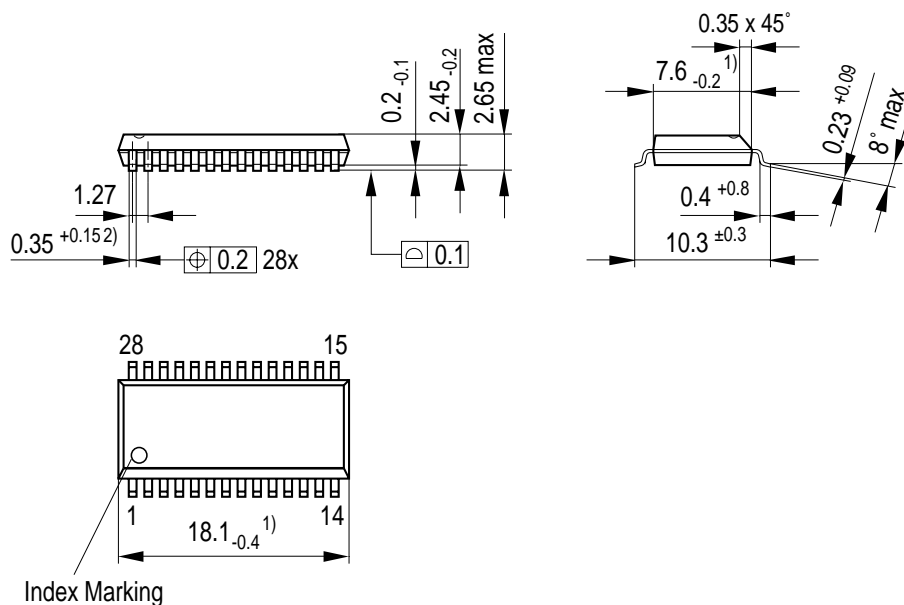


Figure 9 Application Circuit

Package Outlines

P-DSO-28-6

(Plastic Dual Small Outline Package)



- Index Marking
- 1) Does not include plastic or metal protrusions of 0.15 max per side
 - 2) Does not include dambar protrusion of 0.05 max per side

GPS05123

Sorts of Packing

Package outlines for tubes, trays etc. are contained in our Data Book "Package Information".

SMD = Surface Mounted Device

Dimensions in mm

This datasheet has been download from:

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Datasheets for electronics components.